

FIG. 1A

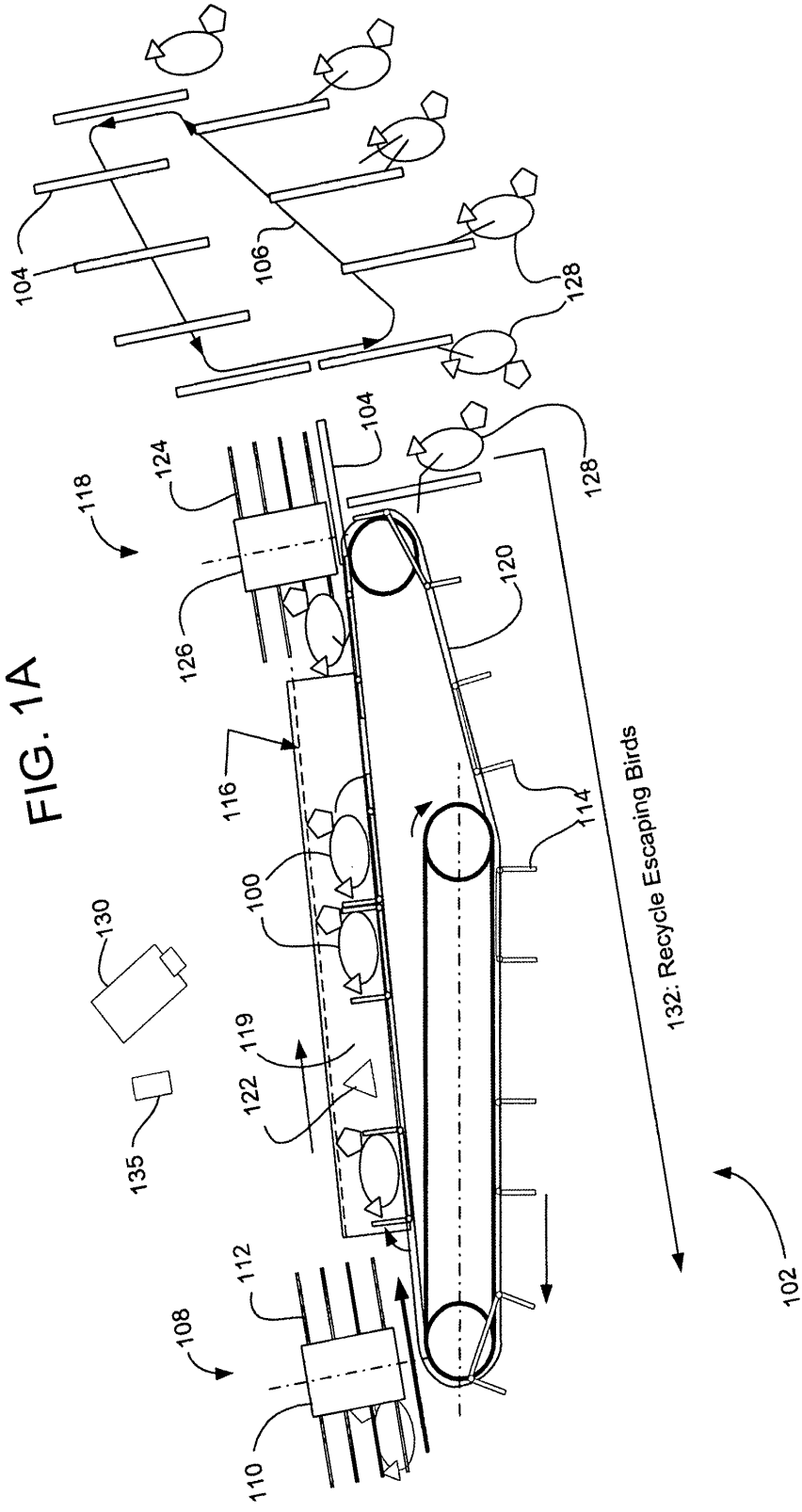


FIG. 1B

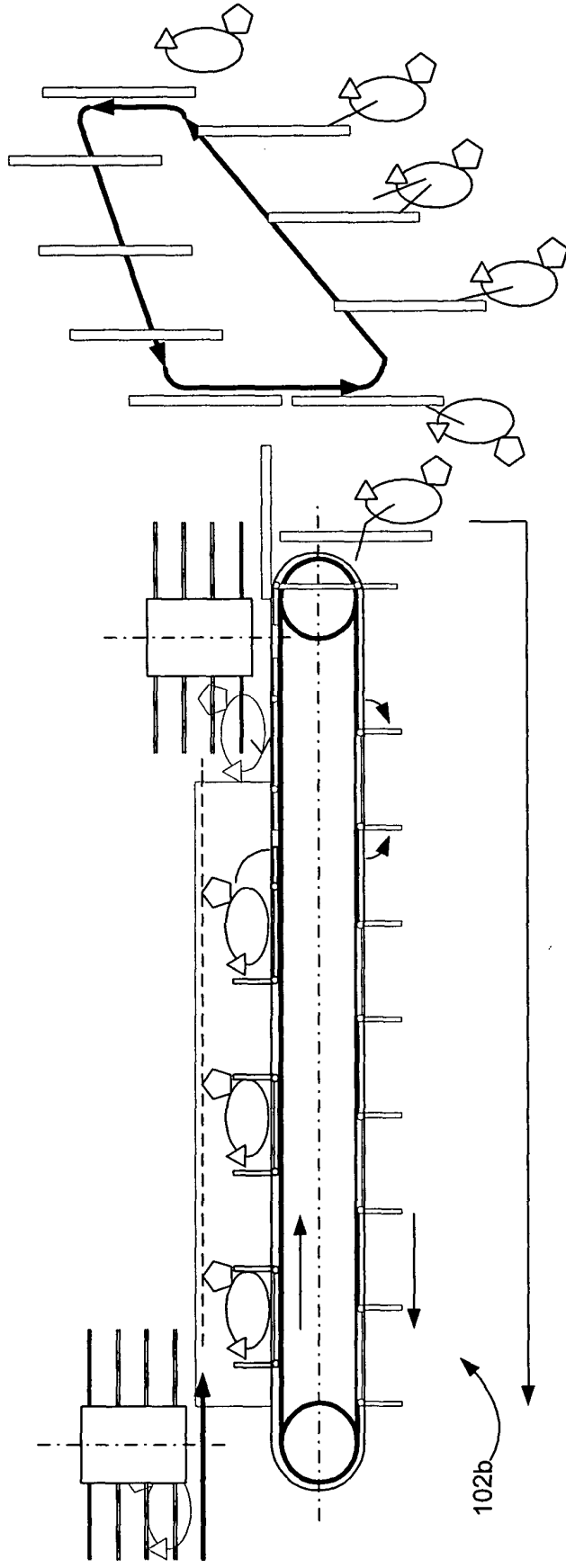


FIG. 1C

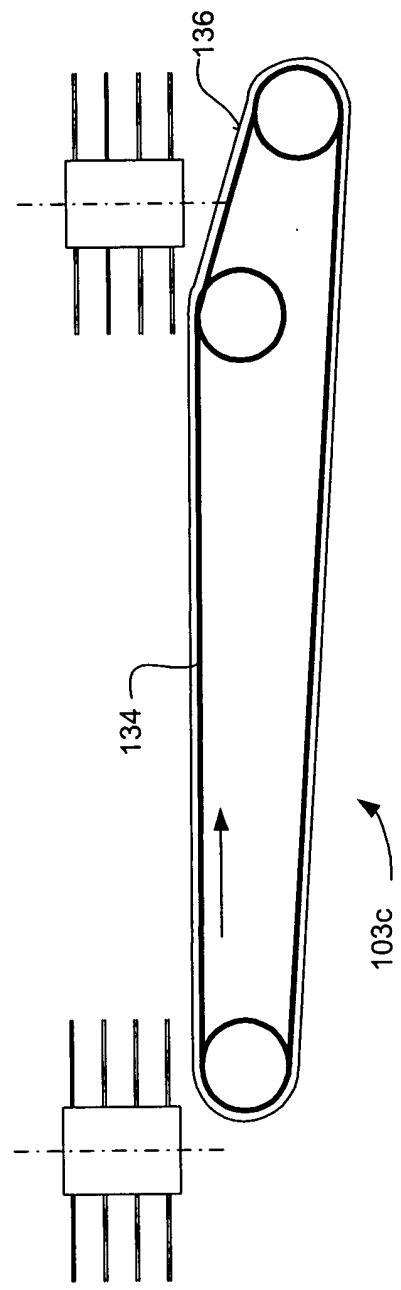


FIG. 2
Singulating System

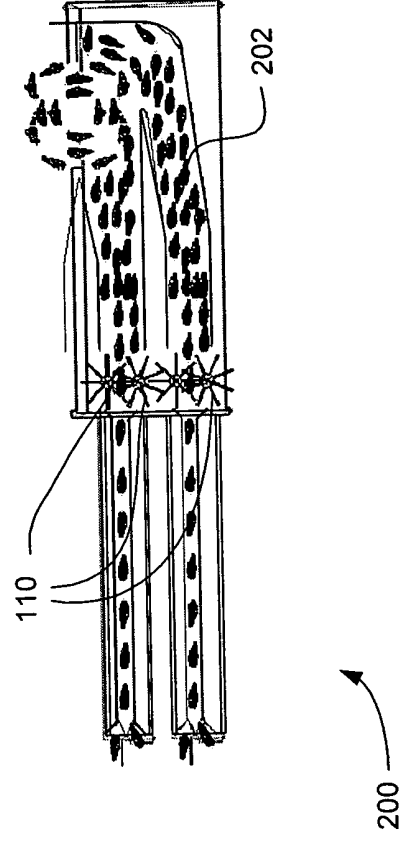


FIG. 3

Pallet

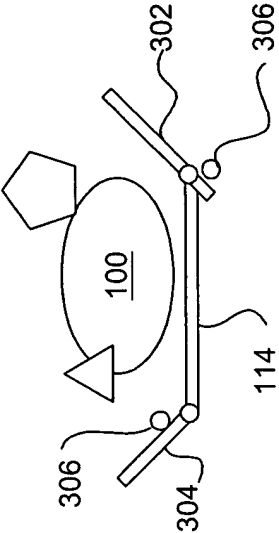


FIG. 4
Leg Gripping

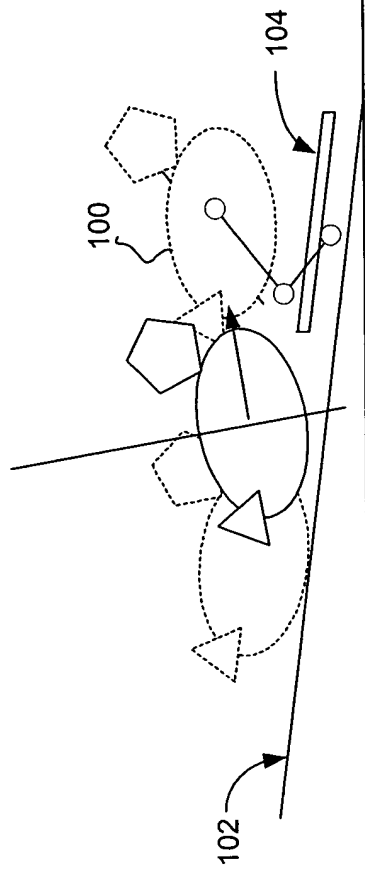


FIG. 5A
Shackle

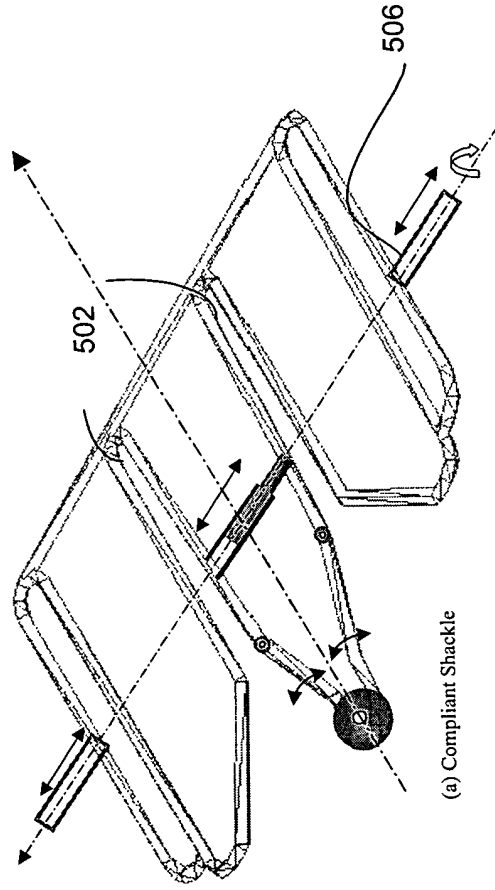


FIG. 5B
Awaiting Shackle

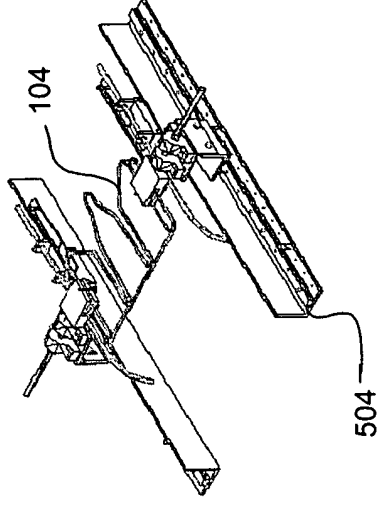


FIG. 5C
Rotated Shackle

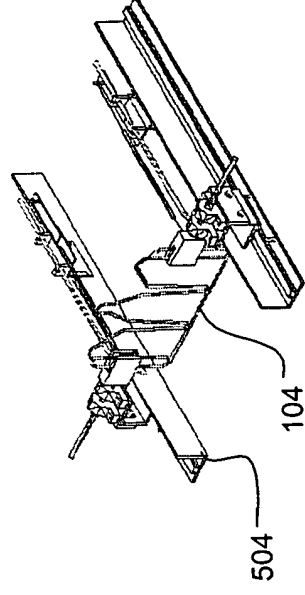


FIG. 6

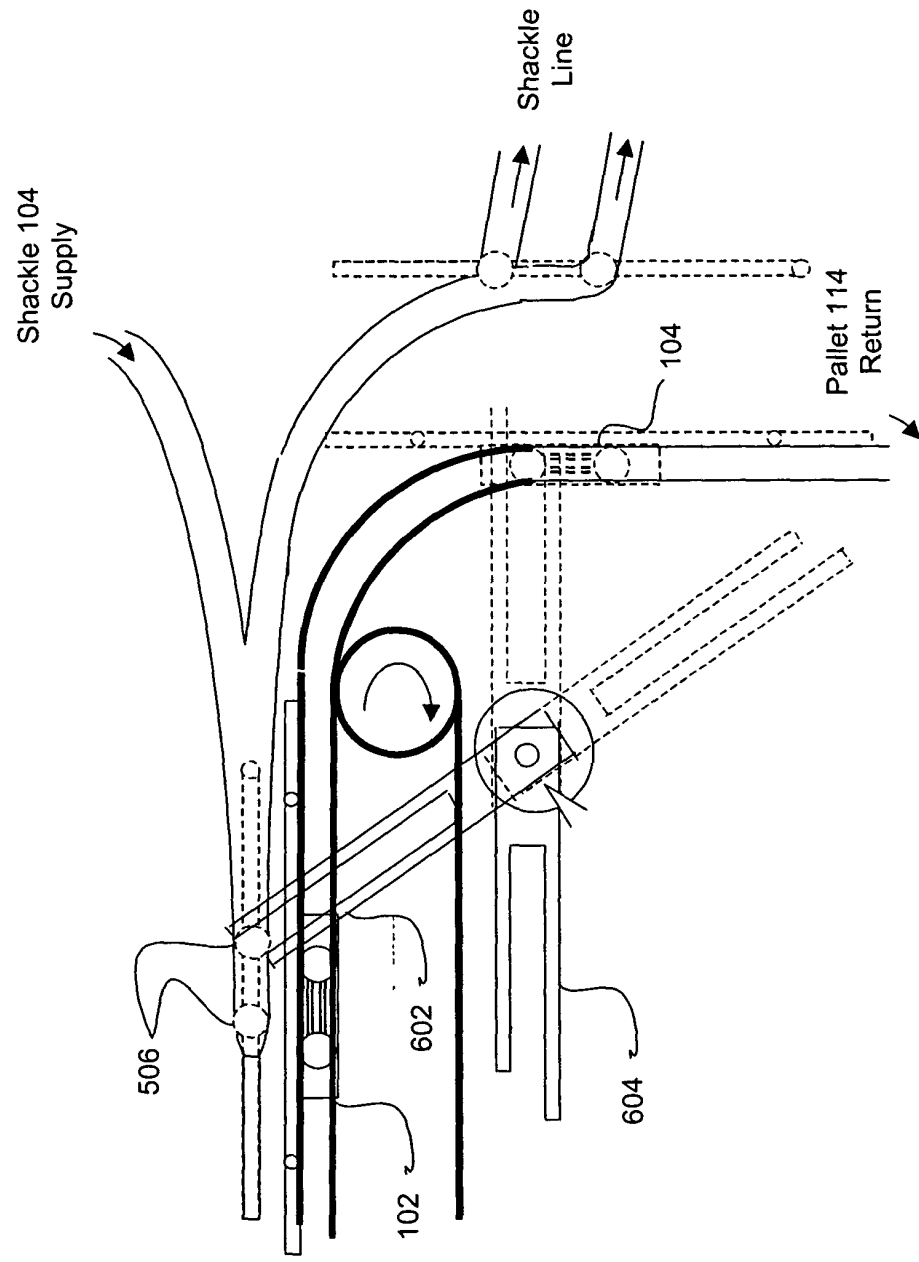


FIG. 7A

Imaging System

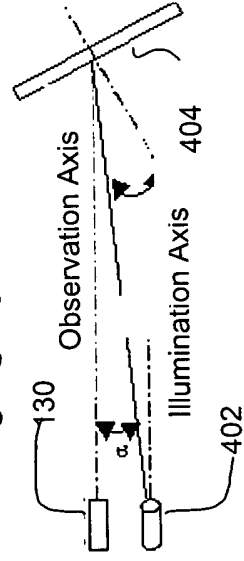


FIG. 7B
Imaging Neural
Network

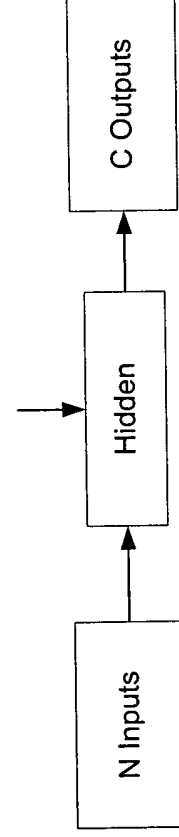


FIG. 7C
Imaging Neural
Network

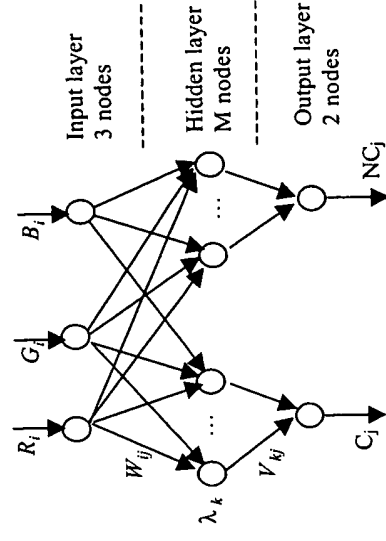


FIG. 8A
Plots for Use with
a Neural Network

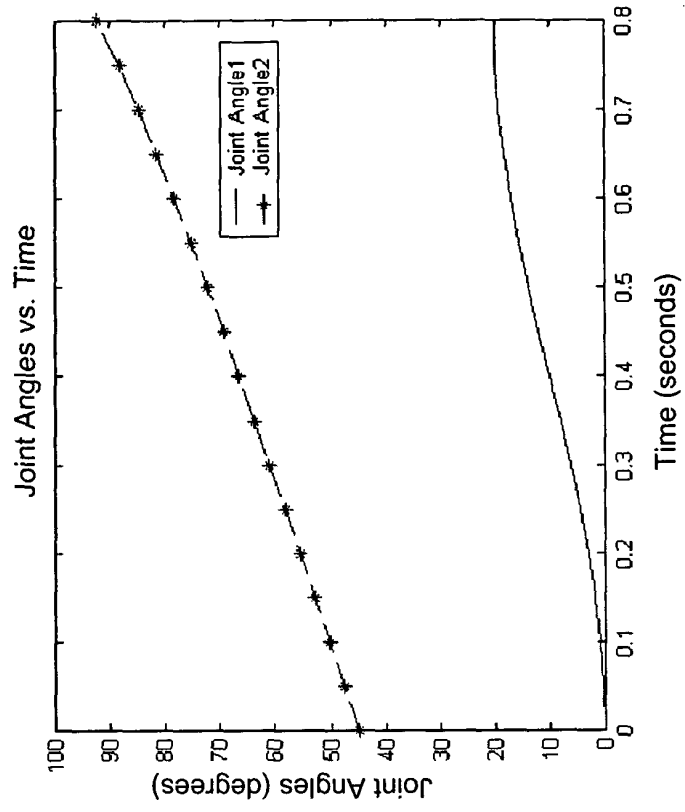
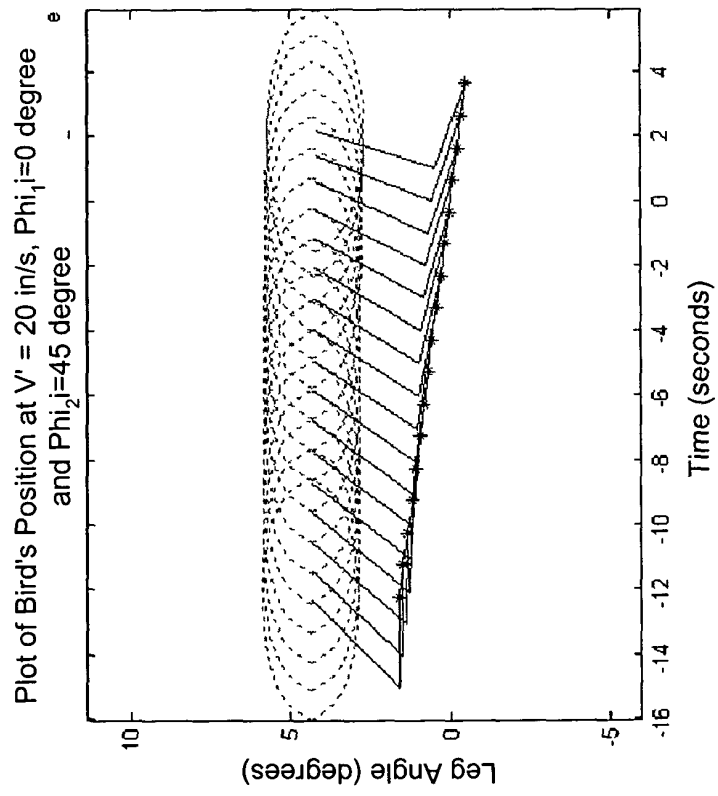


FIG. 8B
 Plots for Use with
 a Neural Network

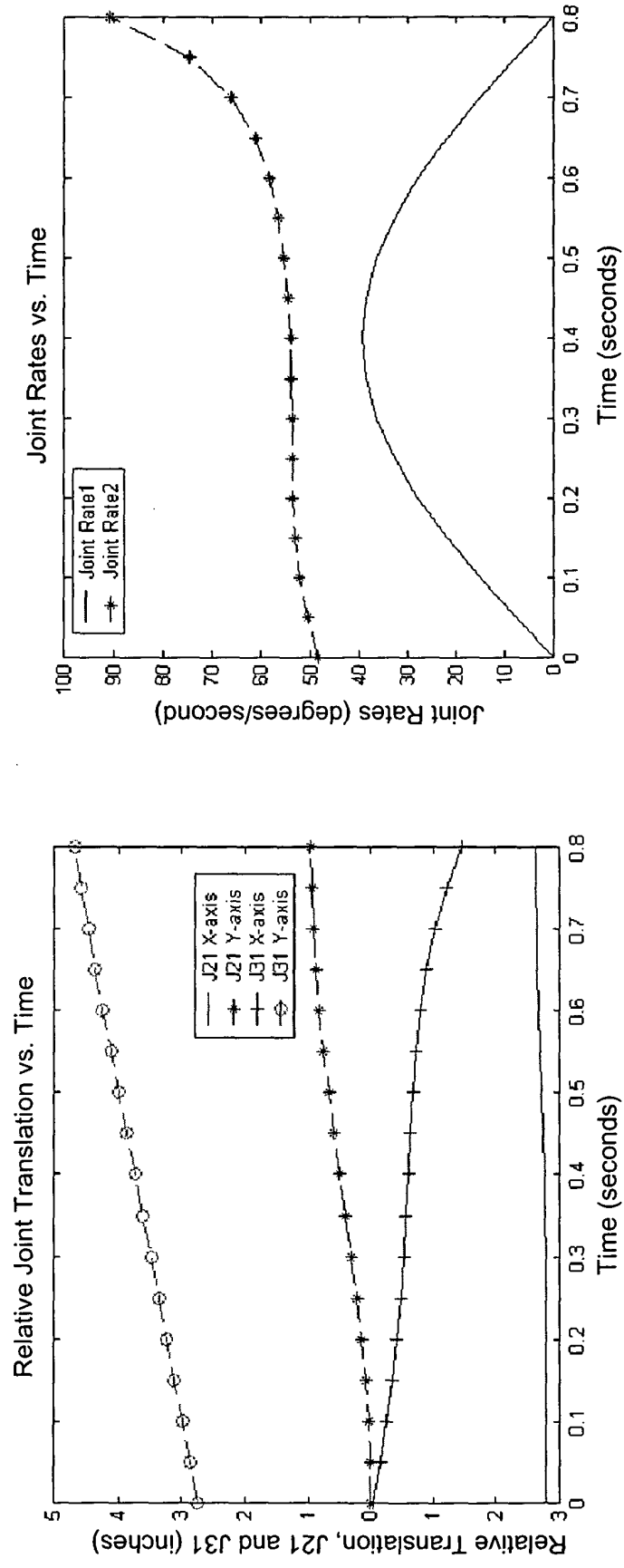


FIG. 8C
Plots for Use with
a Neural Network

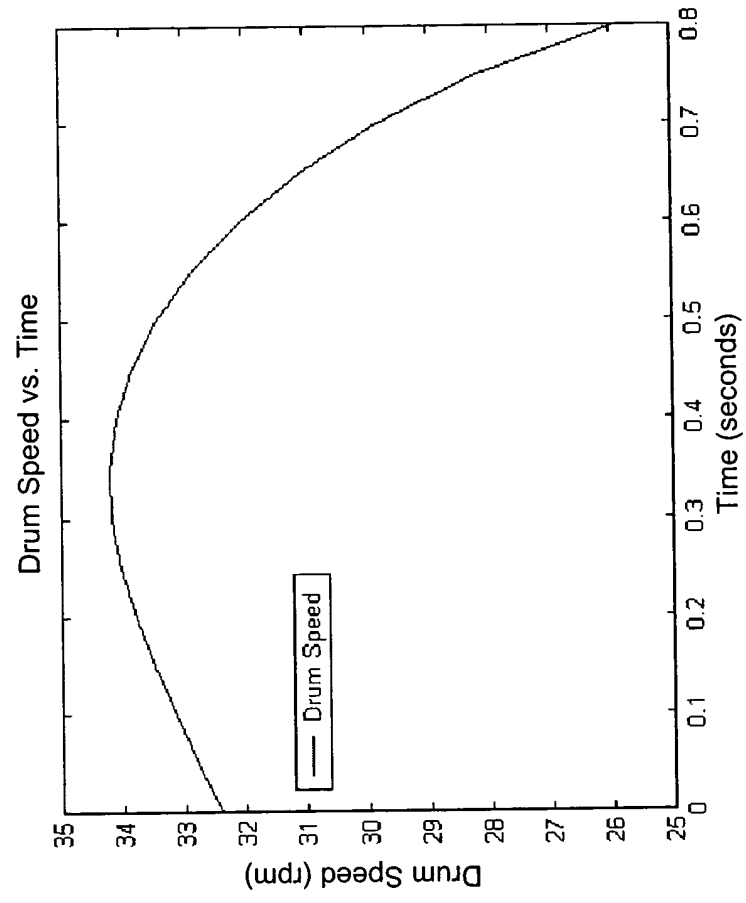


FIG. 9
System Operation Control Sequence

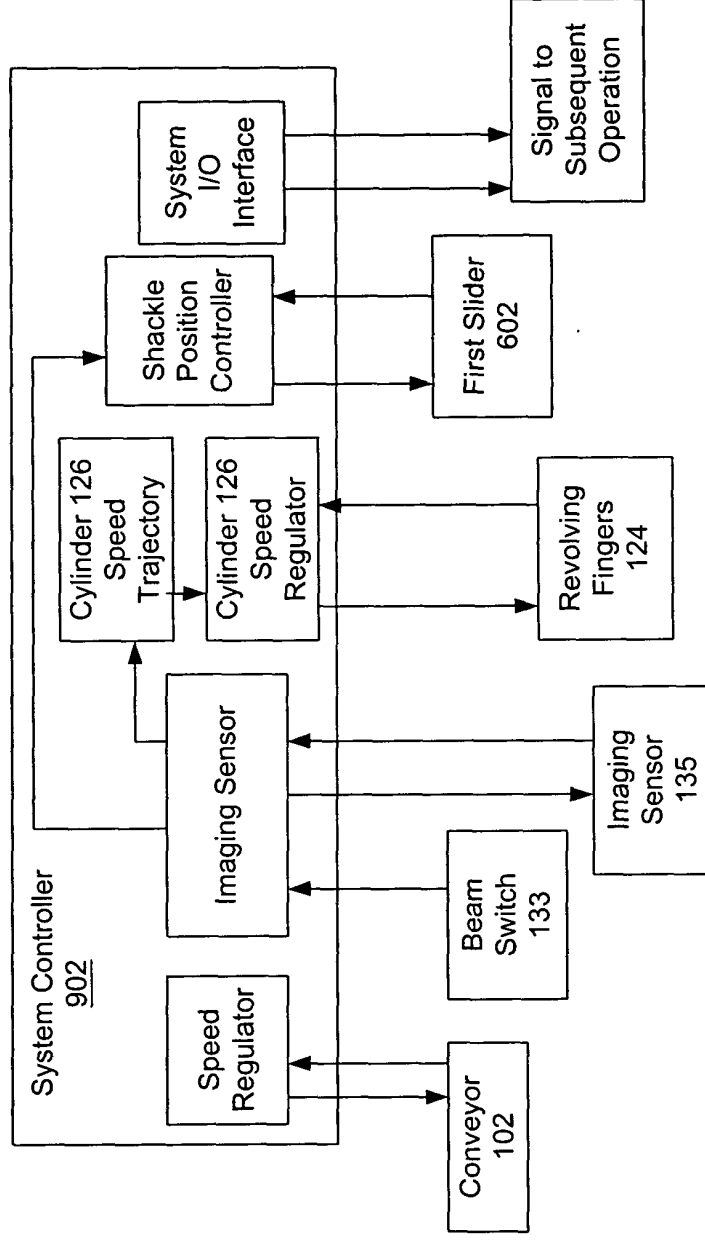


FIG. 10

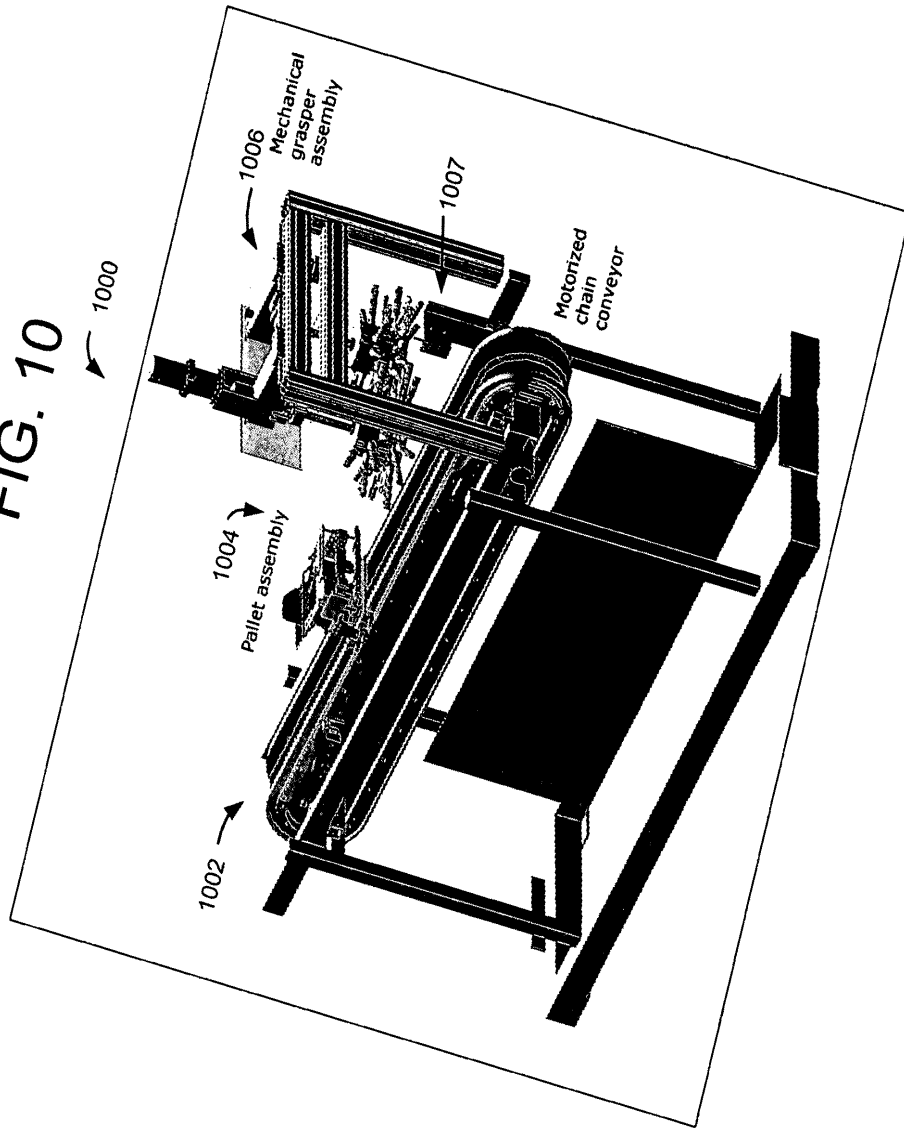
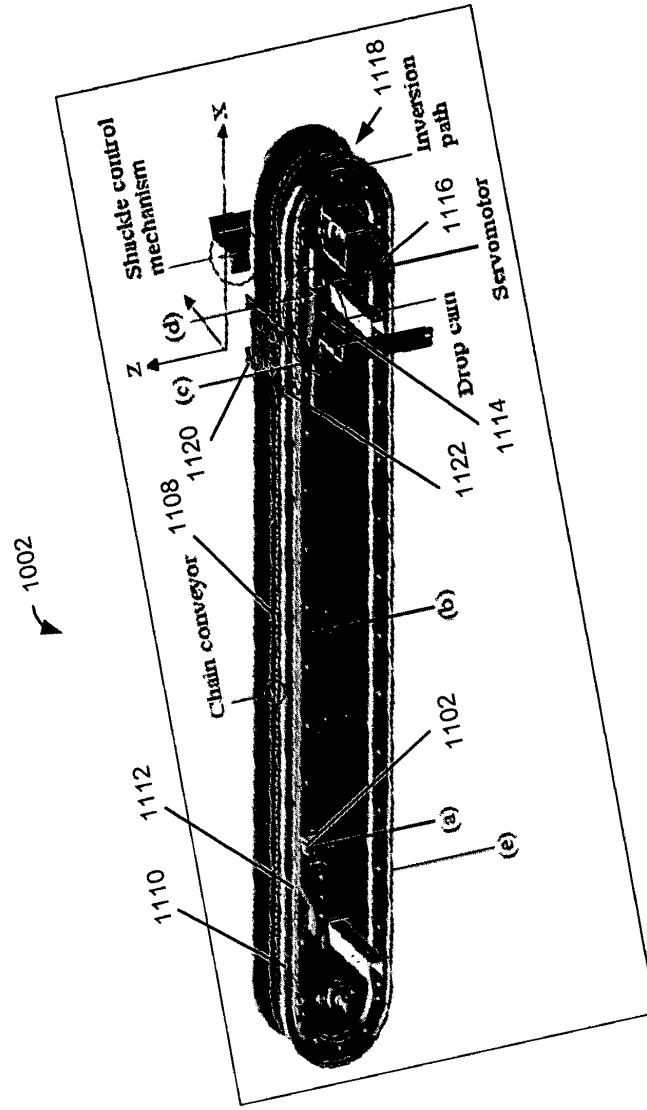


FIG. 11



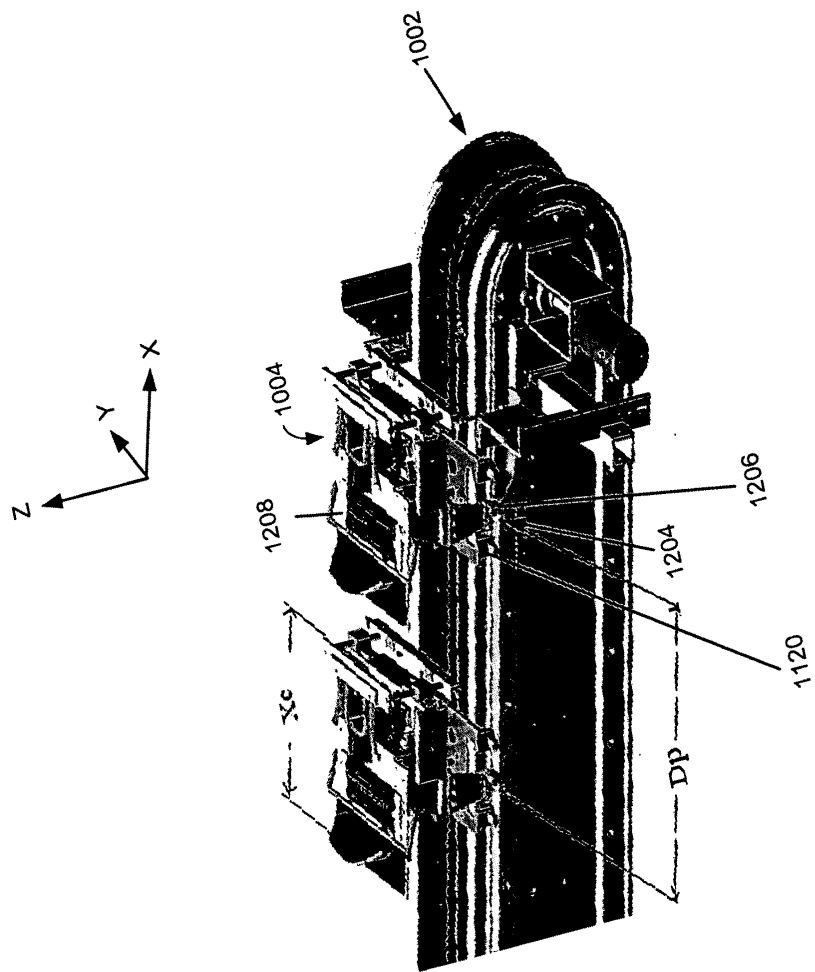


FIG. 12

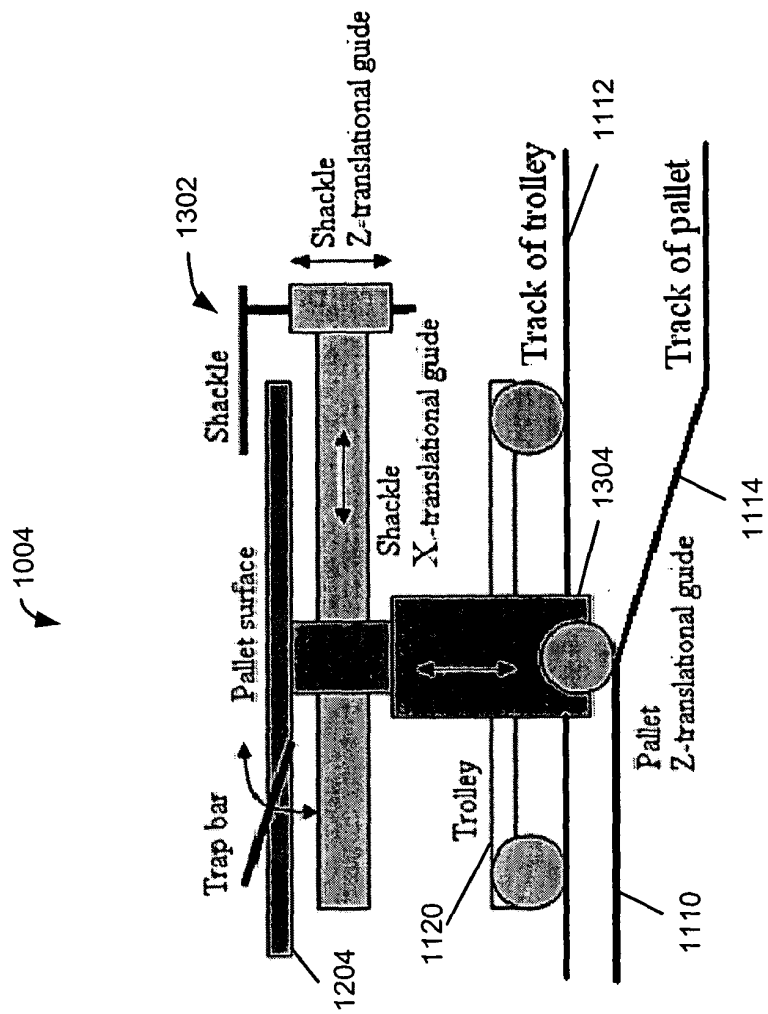


FIG. 13A

FIG. 13B

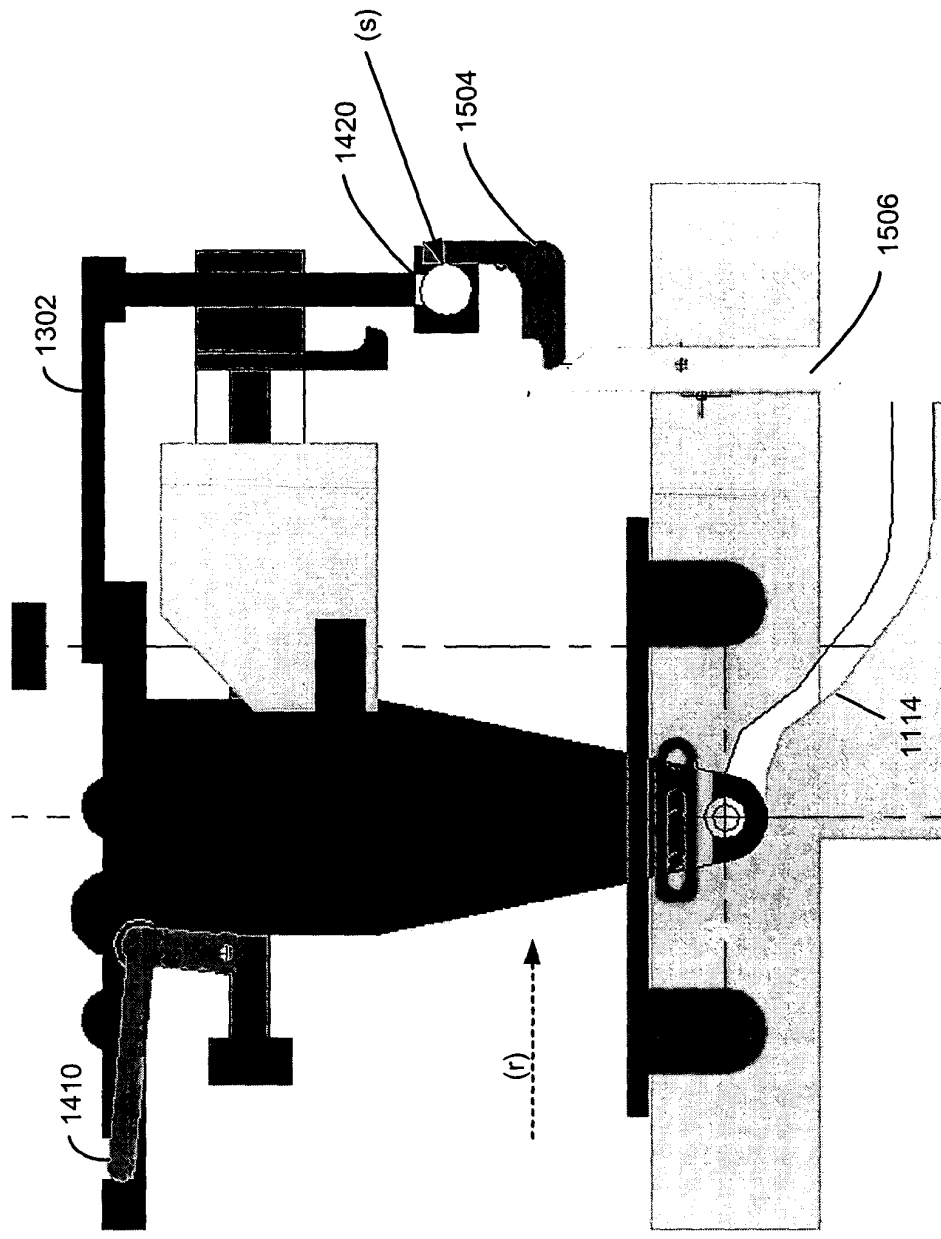


FIG. 13C

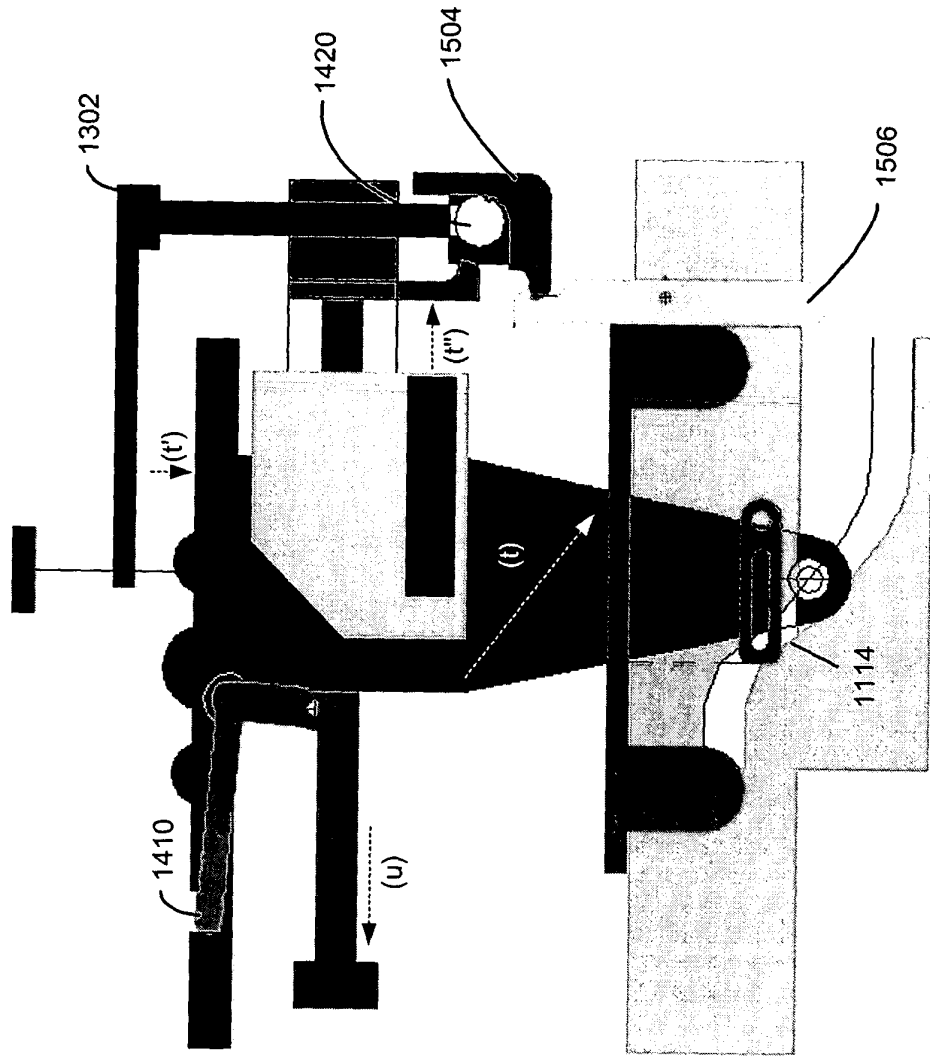


FIG. 13D

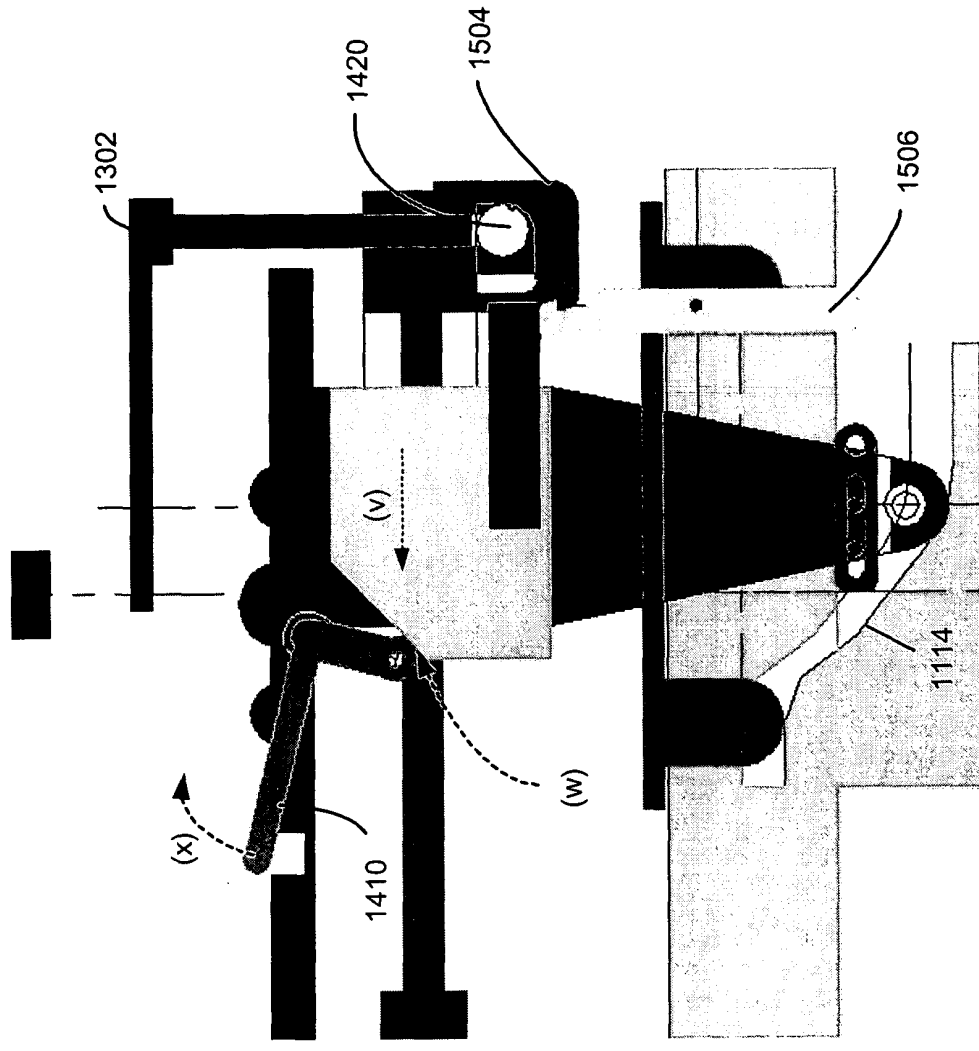


FIG. 13E

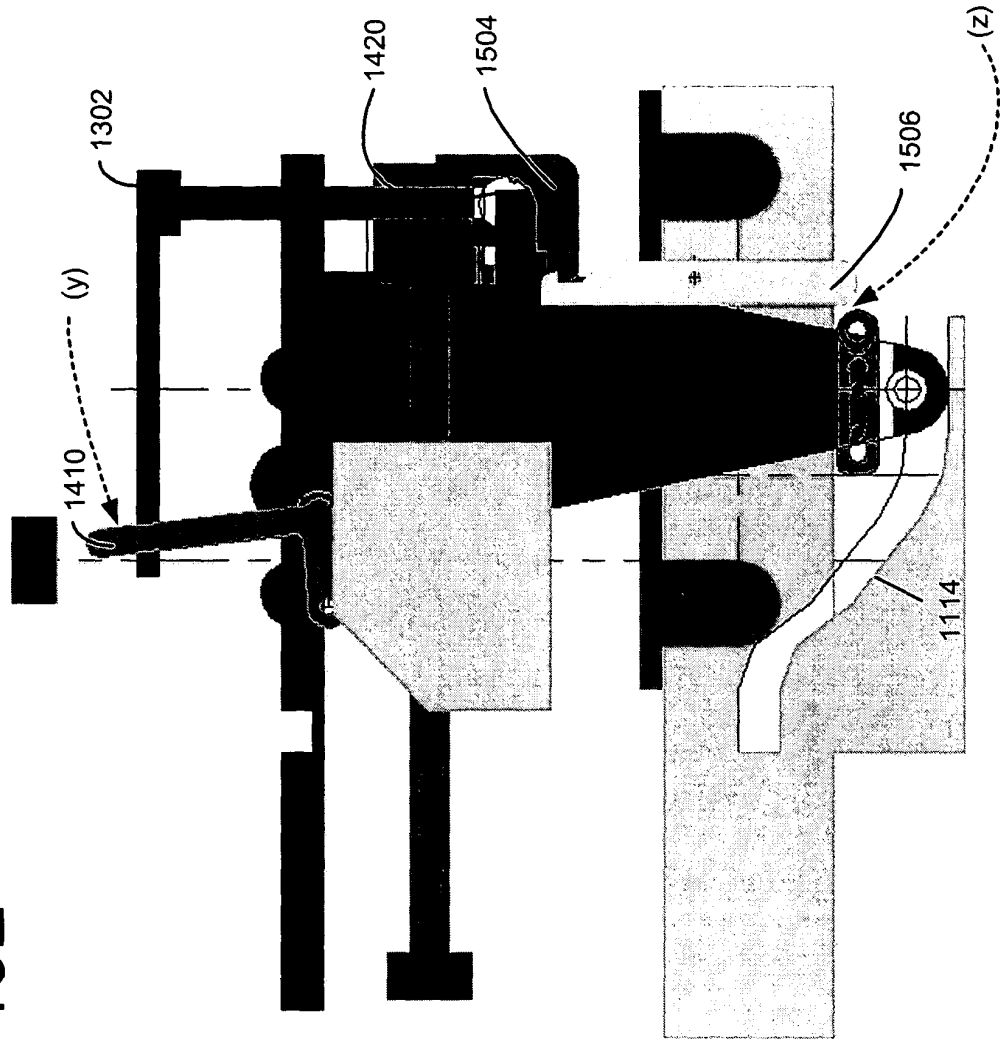
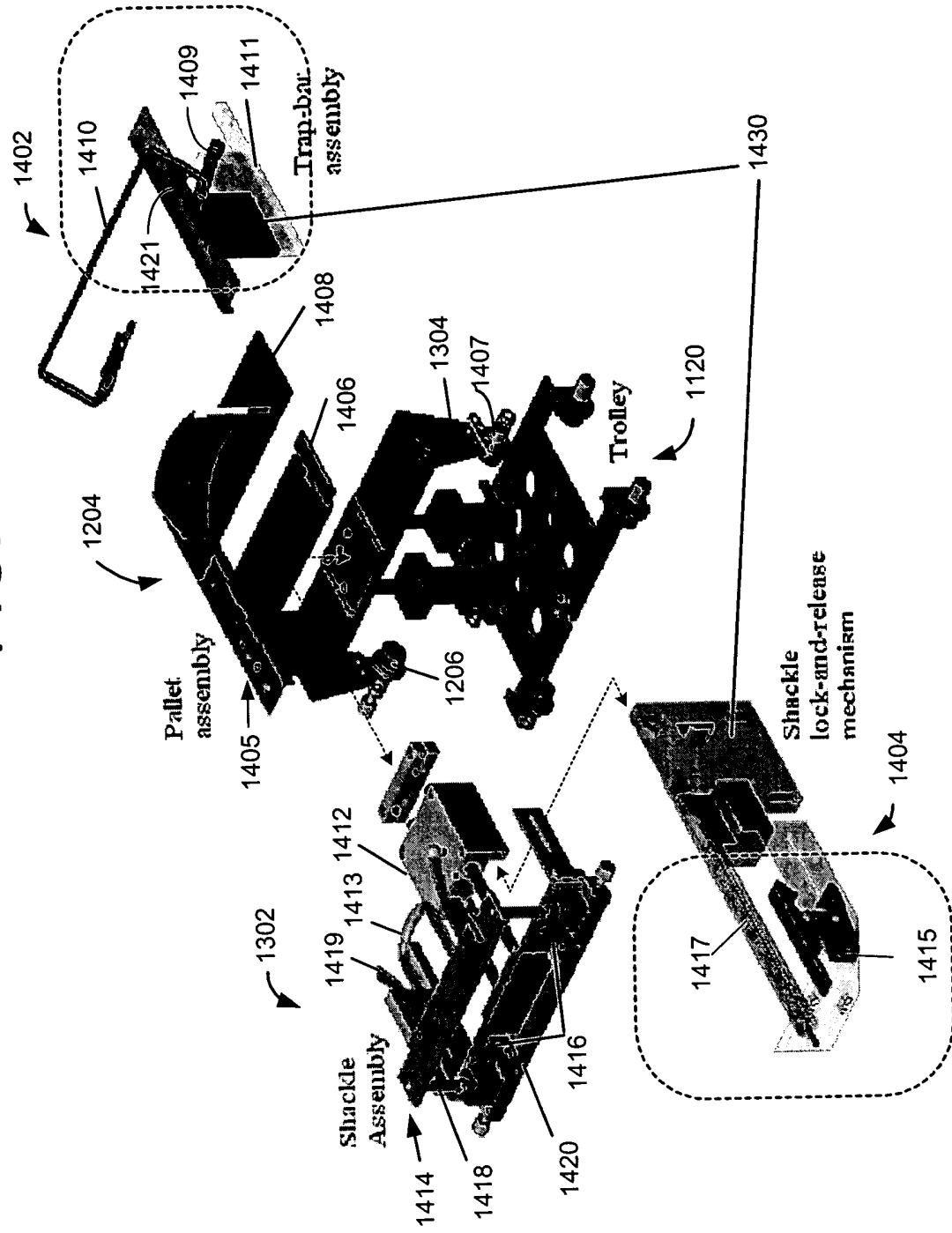


FIG. 14A



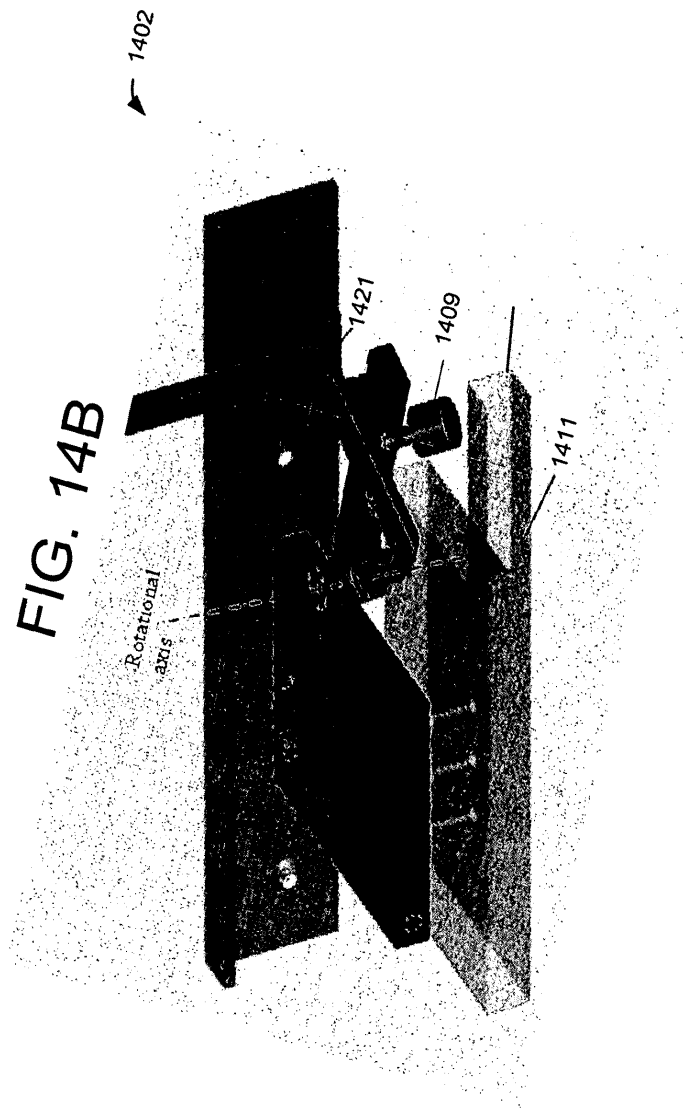


FIG. 14C

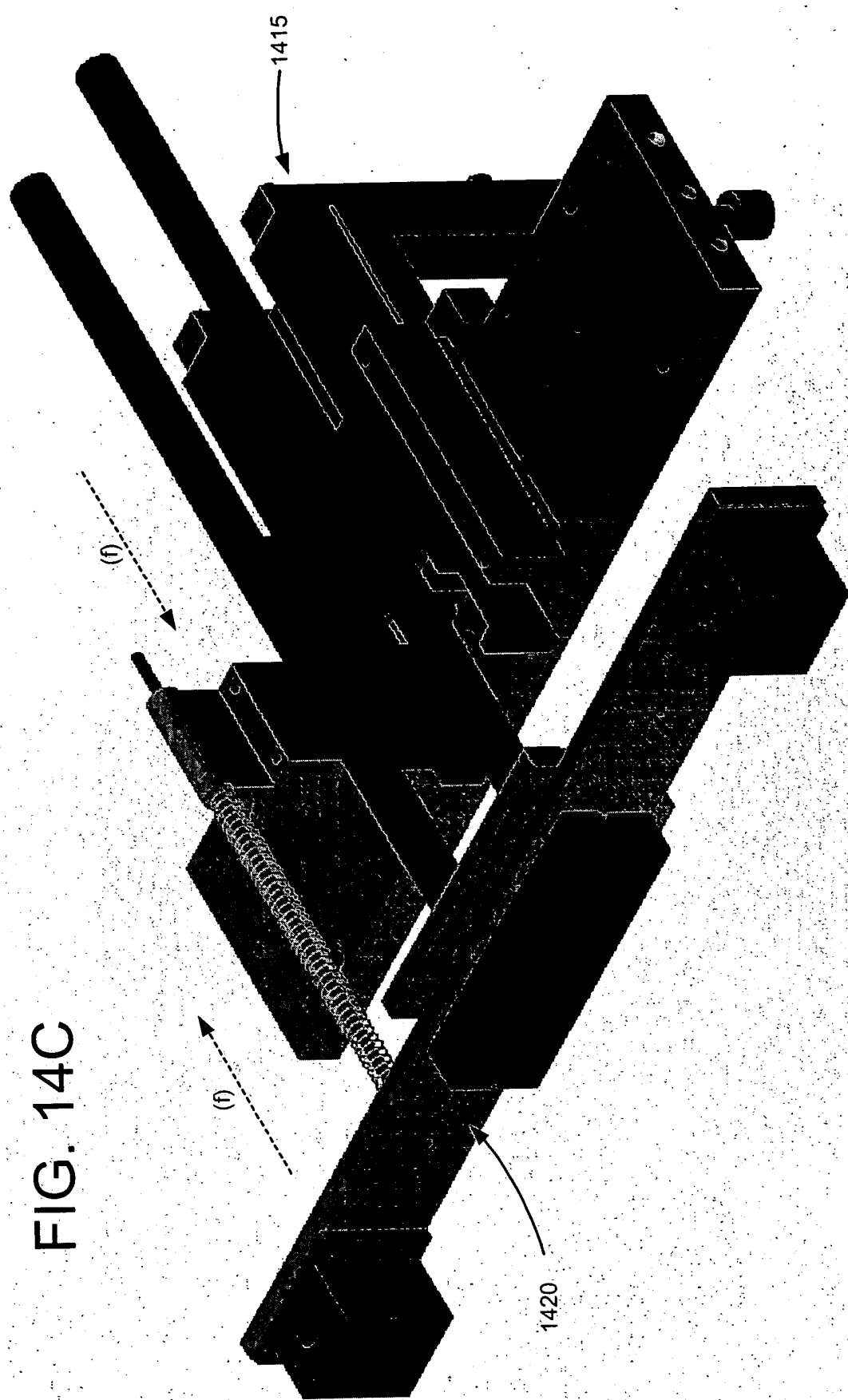
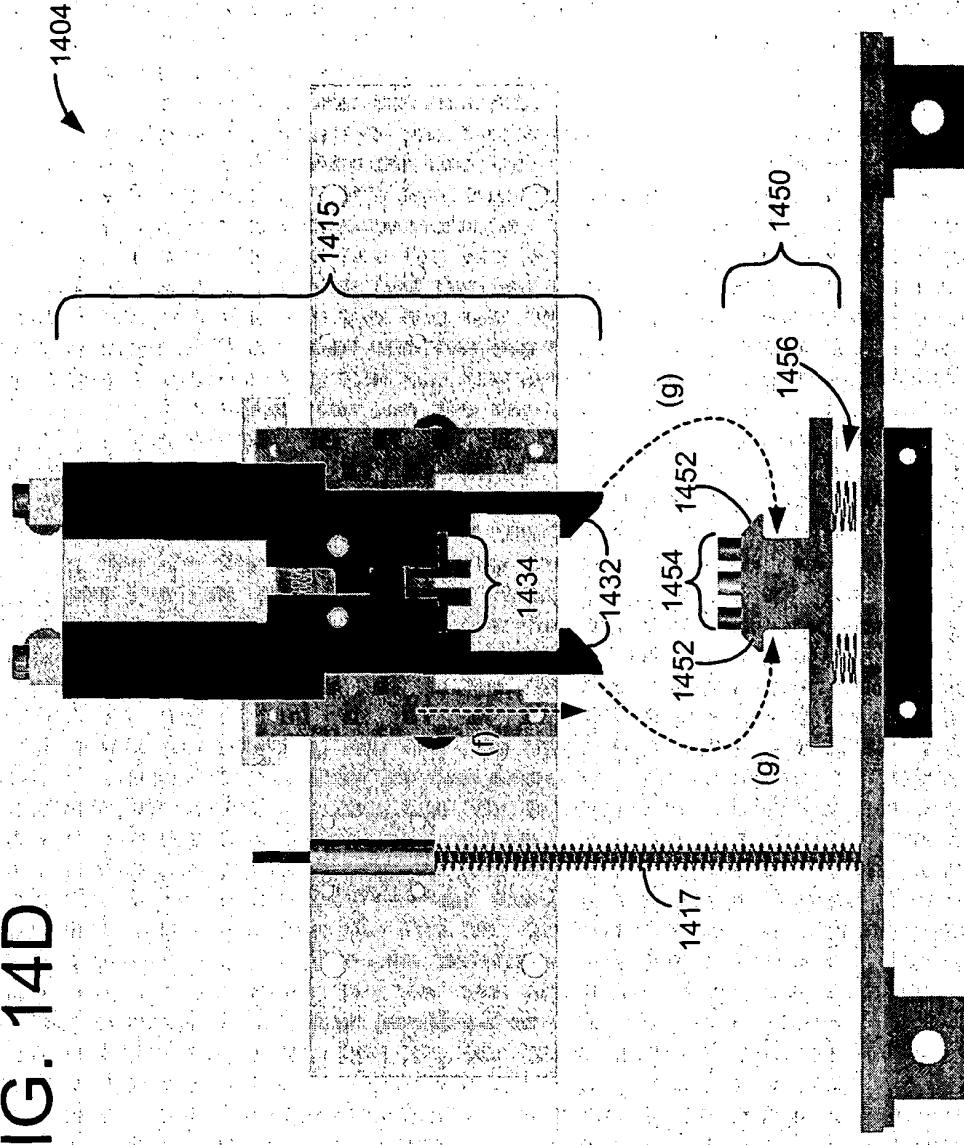


FIG. 14D



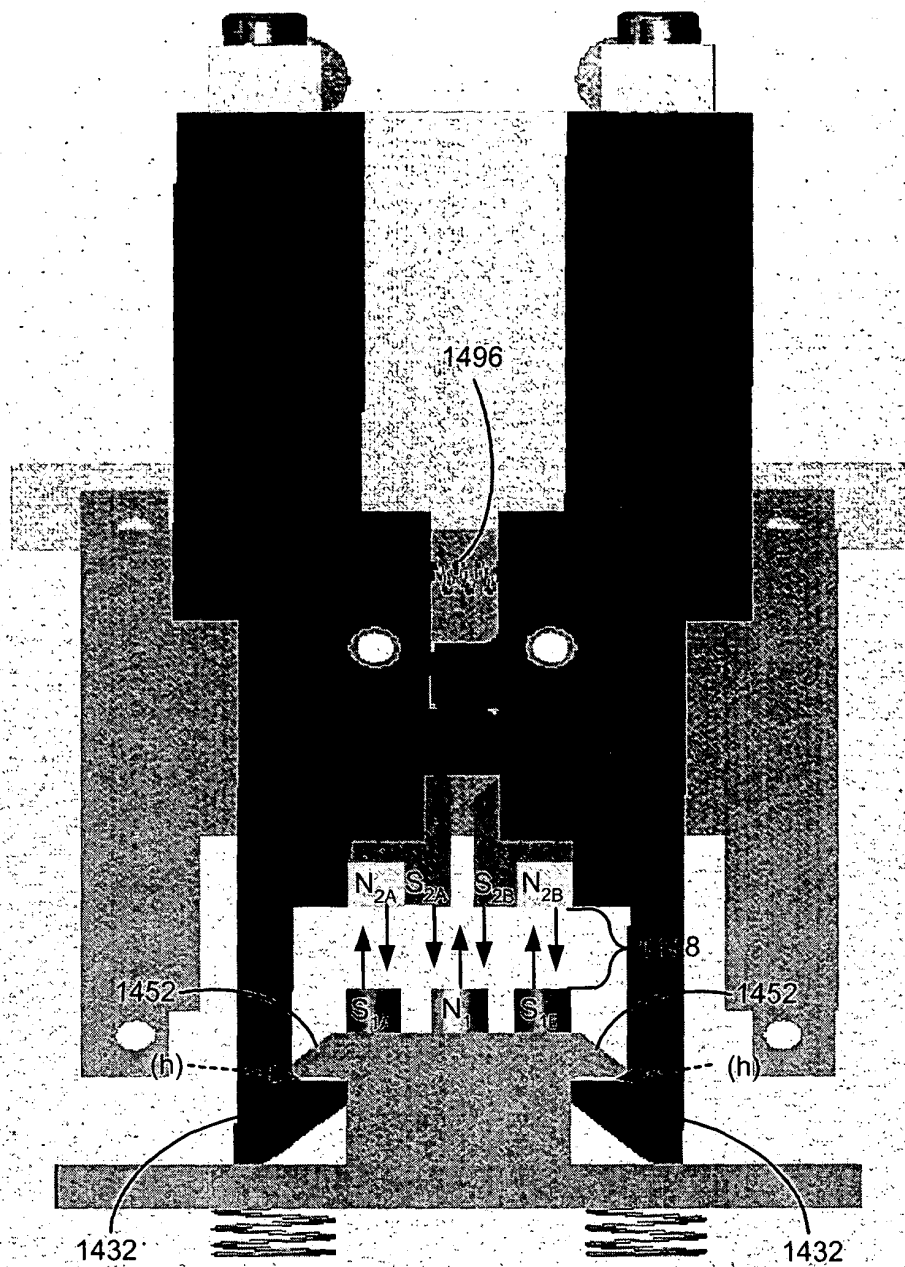


FIG. 14E

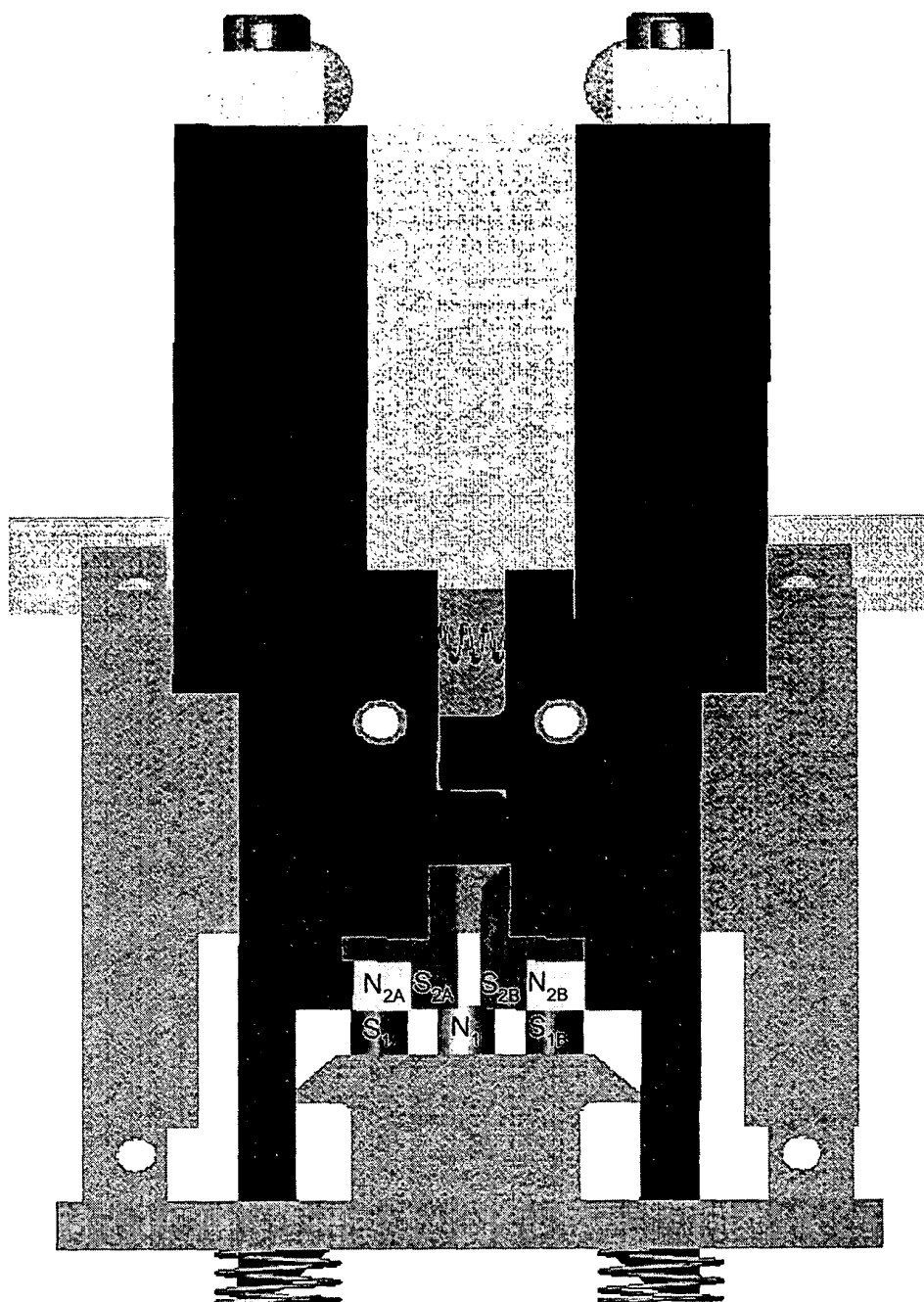


FIG. 14F

FIG. 14G

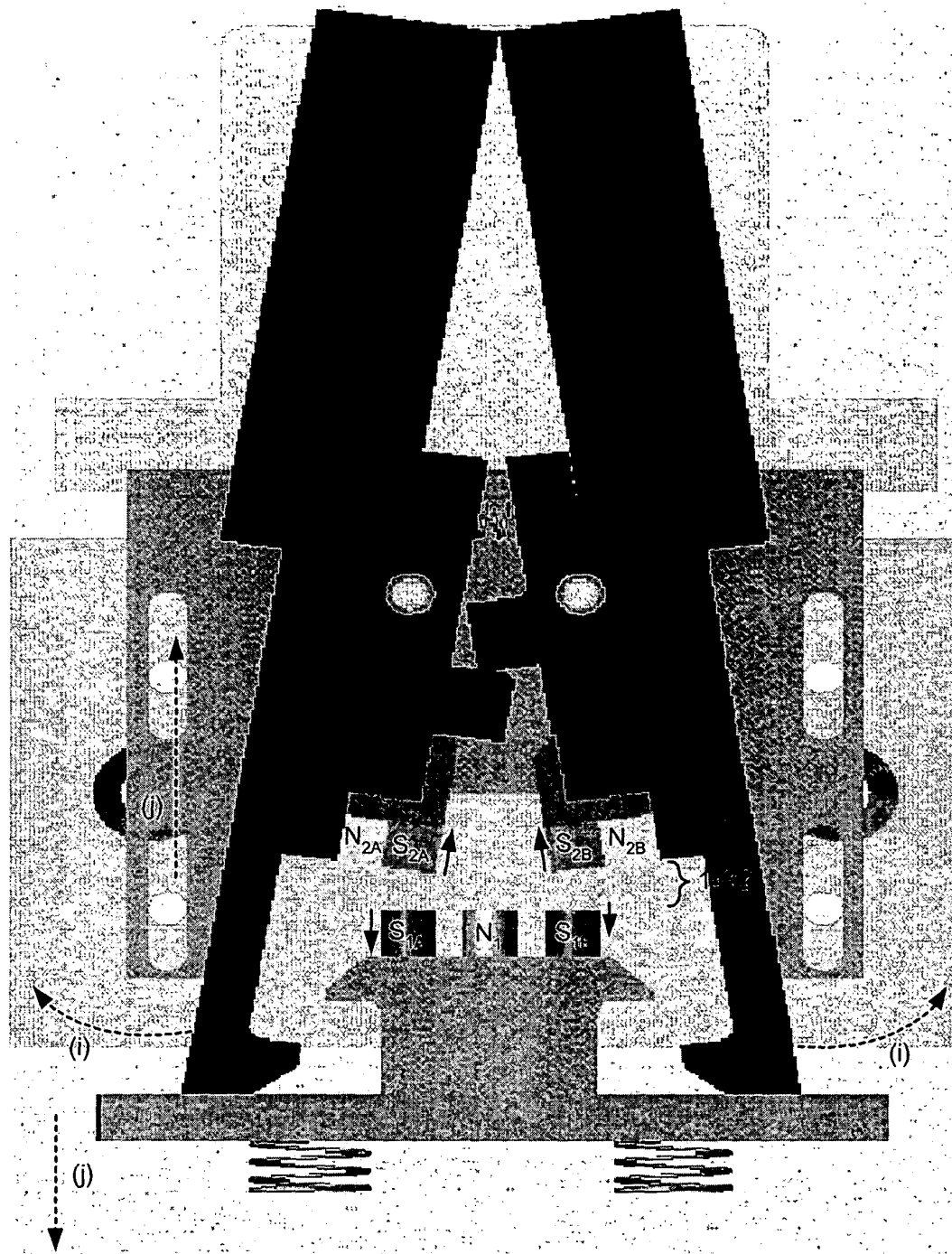
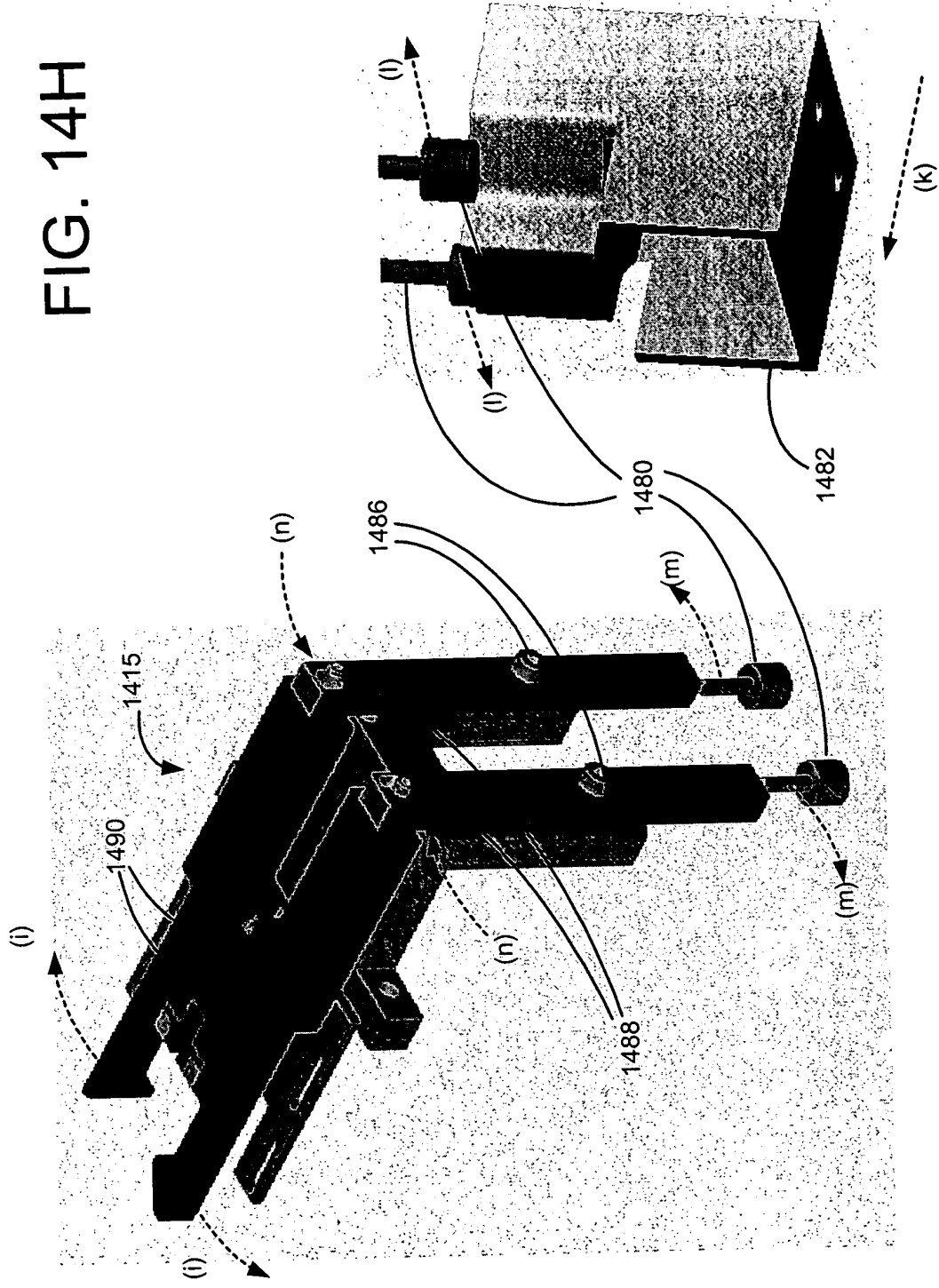


FIG. 14H



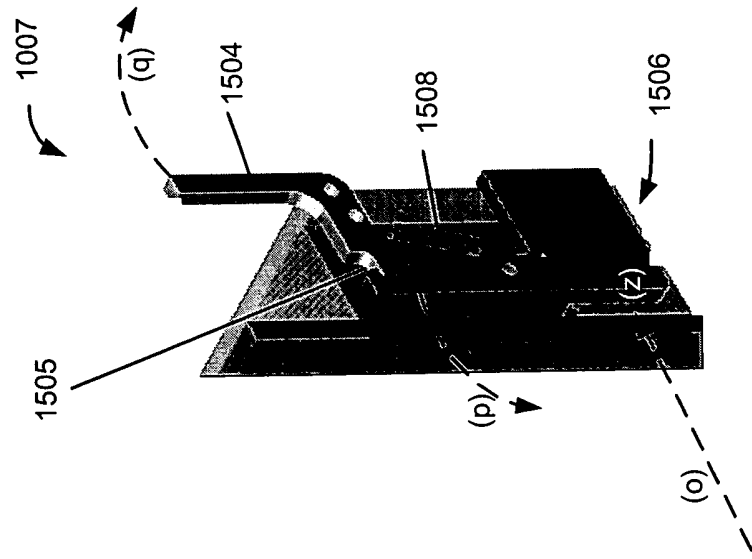


FIG. 15

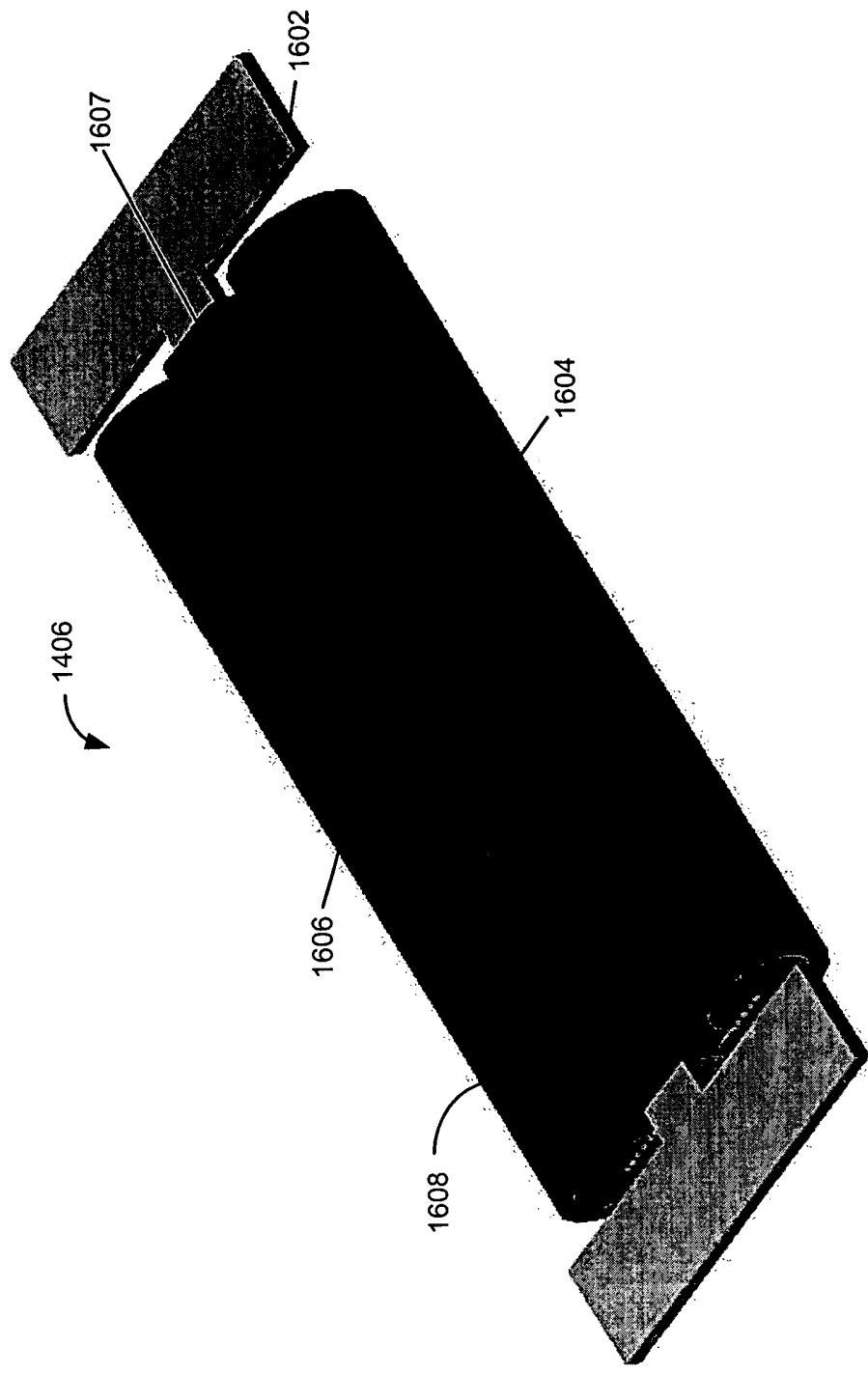


FIG. 16

FIG. 17

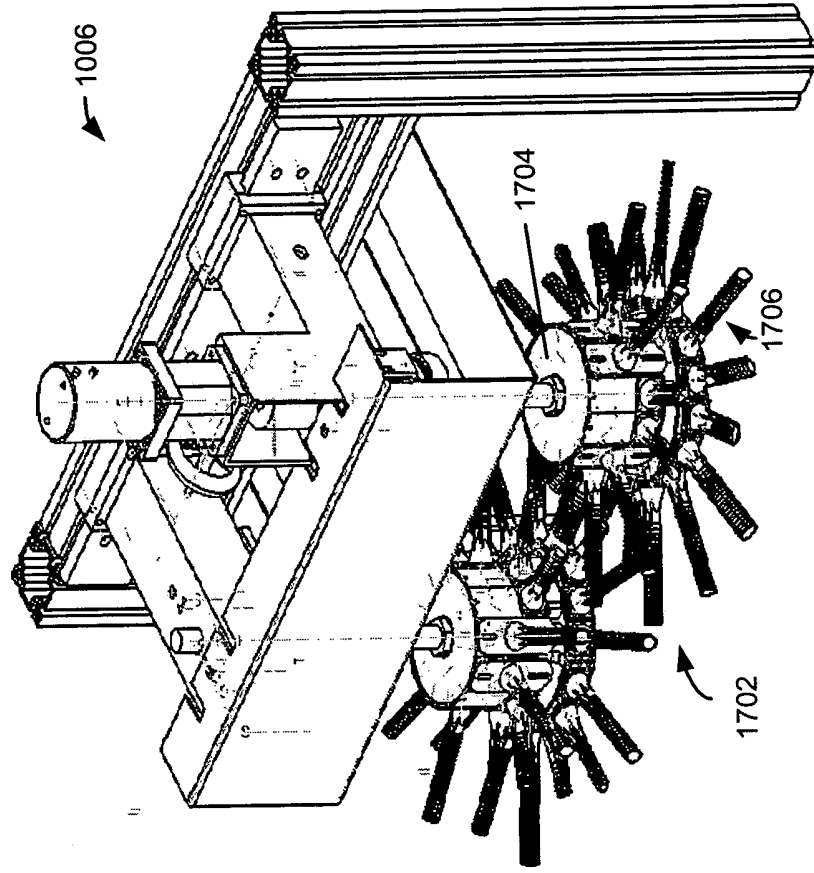


FIG. 18

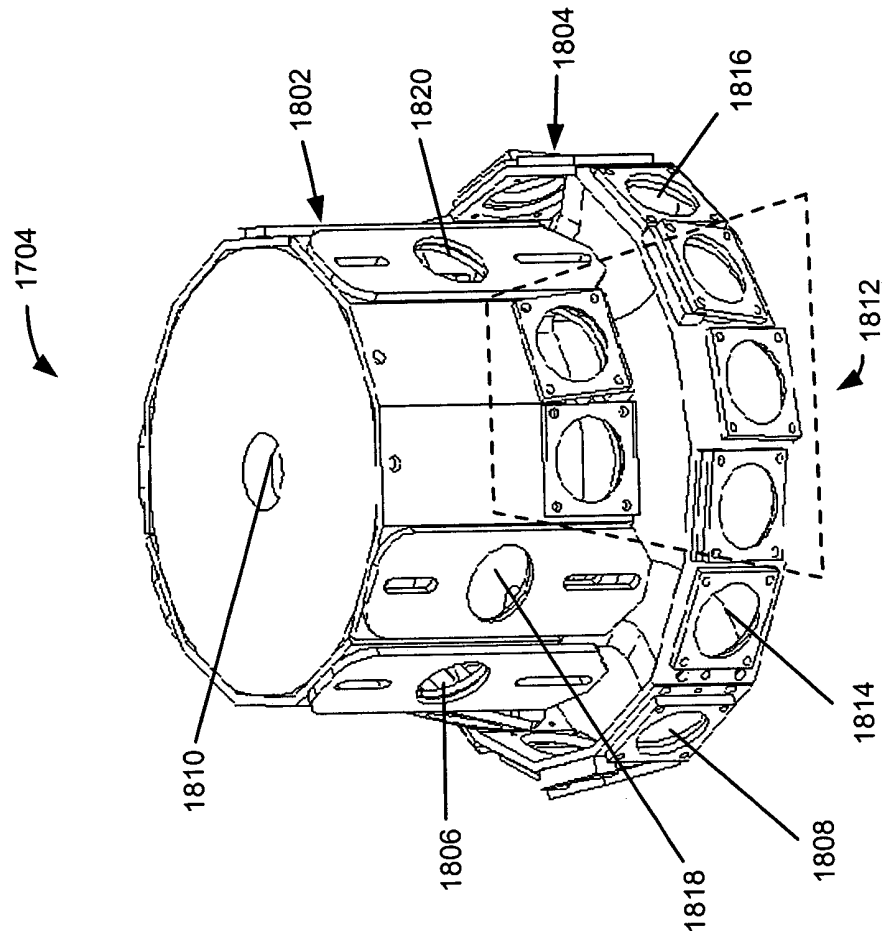
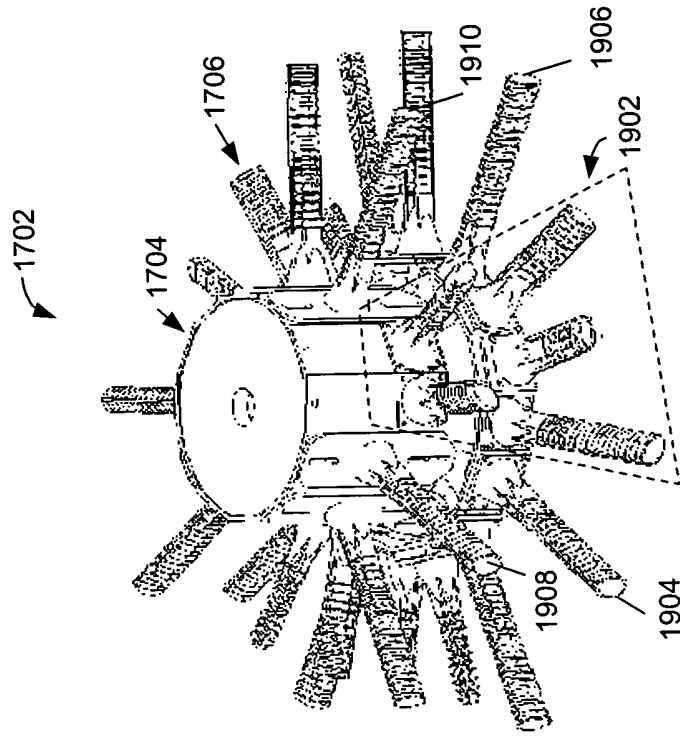


FIG. 19



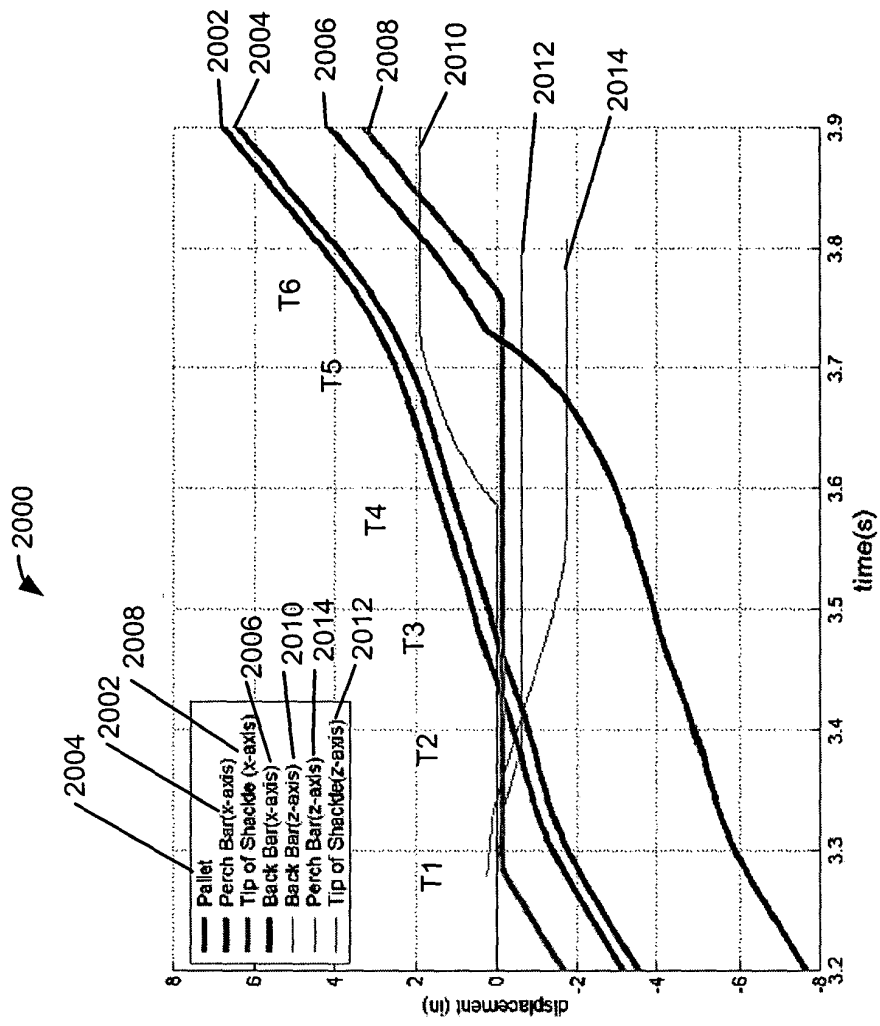


FIG. 20

FIG. 21

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